

Graph Processing System with Multi-level Architecture

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Modern systems for (big) graph processing

Parallel Boost Graph Library, Pregel, CuSha, GraphCT, NetworkX, PowerGraph, graph-tool, GraphBLAS, KDT, igraph, STINGER, Ligra, Gunrock, Help, GPS, Galois, Green-Marl, Gephi, Medusa, MapGraph, NetworKit, SNAP, GraphLab, Giraph, JUNG, Pajek, GraphPad, PEGASUS, GraphX, GraphChi, Totem, Vertexapi2

+ a lot of papers dedicated to performance engineering of well-known graph algorithms

Classification of graph processing systems

Different graph processing models

- Vertex-centric
- Domain-specific languages
- Processing primitives

Vertex-centric model

“Thinking like a vertex”

Each vertex

- Has some data about itself, ingoing and outgoing edges and make some computations
- Use ingoing edges to receive messages from other vertices
- Use outgoing edges to send messages to other vertices

Pros

- Natural way to parallelize your application

Cons

- Bad suitable for some algorithms (adjacency matrix-based)

First implementation

- Pregel (Google, 2010)

Domain-specific Language

Domain-specific language is a computer language specialized to a particular application domain.

- User develops program using specific domain terminology
- Compiler translates DSL code to target programming language (for instance, C++ or CUDA)

Pros

- Increasing developer productivity
- Cross-platform

Cons

- It is hard to integrate DSL code in application that developed using other programming language

Domain-specific Language

Green-Marl – DSL for graph processing on shared memory systems

- Has C/C++ compiler

Other implementations

- PowerGraph
- Galois
- GraphChi
- GraphLab

```
1 Procedure Compute_BC(  
2   G: Graph, BC: Node_Prop<Float>(G)) {  
3   G.BC = 0;           // initialize BC  
4   Foreach(s: G.Nodes) {  
5     // define temporary properties  
6     Node_Prop<Float>(G) Sigma;  
7     Node_Prop<Float>(G) Delta;  
8     s.Sigma = 1; // Initialize Sigma for root  
9     // Traverse graph in BFS-order from s  
10    InBFS(v: G.Nodes From s)(v!=s) {  
11      // sum over BFS-parents  
12      v.Sigma = Sum(w: v.UpNbrs) {w.Sigma};  
13    }  
14    // Traverse graph in reverse BFS-order  
15    InRBFS(v!=s) {  
16      // sum over BFS-children  
17      v.Delta = Sum (w:v.DownNbrs) {  
18        v.Sigma / w.Sigma * (1+ w.Delta)  
19      };  
20      v.BC += v.Delta @s; //accumulate BC  
21    } } }
```

Parallel processing primitives

Basic idea

- Select common graph operations
- Implement it as parallel highly optimized building blocks
- Develop graph algorithms as combinations of such primitives

Pros

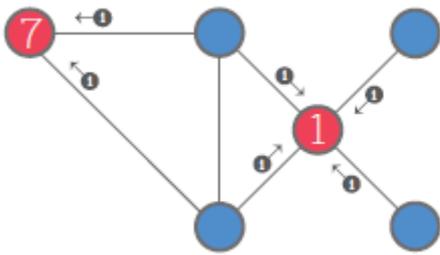
- Simplification of development and debugging
- Developed on common programming languages

Cons

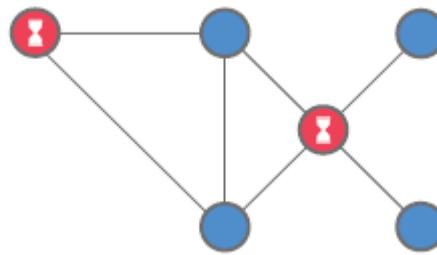
- There is no single complete set of primitives

Parallel processing primitives

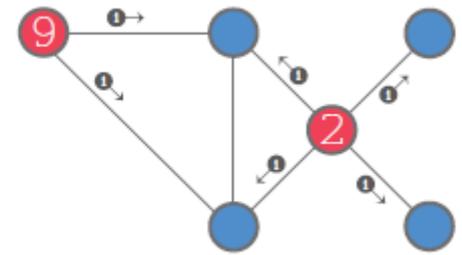
Gather-Apply-Scatter (MapGraph, PowerGraph)



Gather

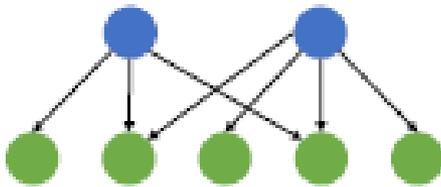


Apply

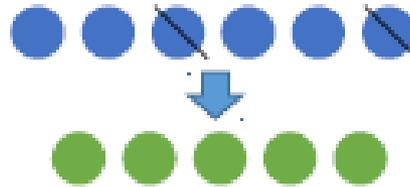


Scatter

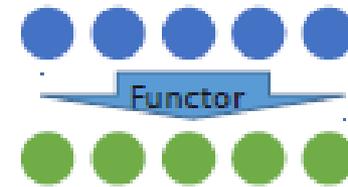
Advance-Filter-Compute (Gunrock)



Advance



Filter

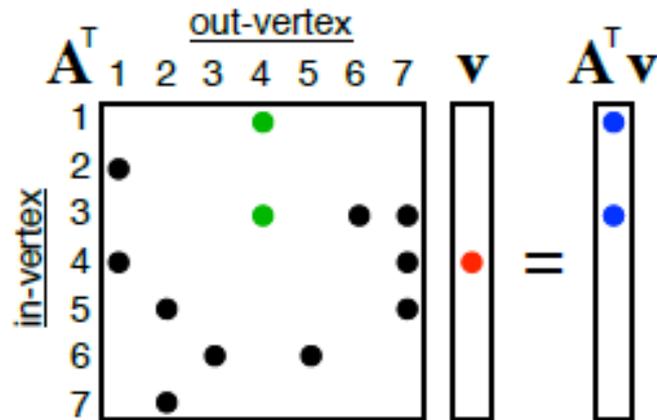
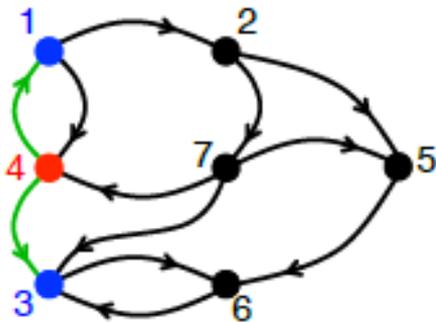


Compute

Parallel processing primitives

GraphBLAS

- Attempt to describe graph algorithms on the language of linear algebra
- Under development since 2008 year



Real-world problems meet graph processing software

Most popular systems are sequential and based on languages like Python, R, etc.

Why researchers don't use parallel big graph processing systems?

- Choose only one feature from the list...
 - Support of various architectures
 - High performance processing
 - A lot of implemented algorithms

My network science

Natural language processing / financial transactions processing

- Detect sets of similar things in network
 - ~100 000 vertices and edges
- Overlapping community detection
 - Find and rank k-cliques

City logistics

- Graphs with parallel edges
 - ~ 100 000 vertices and millions of edges
- Algorithms like max-flow which are sensitive to graph data structure
- Dynamically changing graphs

“Perfect” graph processing system

Ability to use different graph data structures to tune application performance

- Fast topology modification
- Perfect data structure can do $O(1)$

A lot of implemented algorithms

Build graph processing algorithm using functions

Ability of parallelization

Proposed multi-layer architecture

Algorithms level

- High-level operations on graph

Graph representation

- Storage for nodes and edges

Data structure

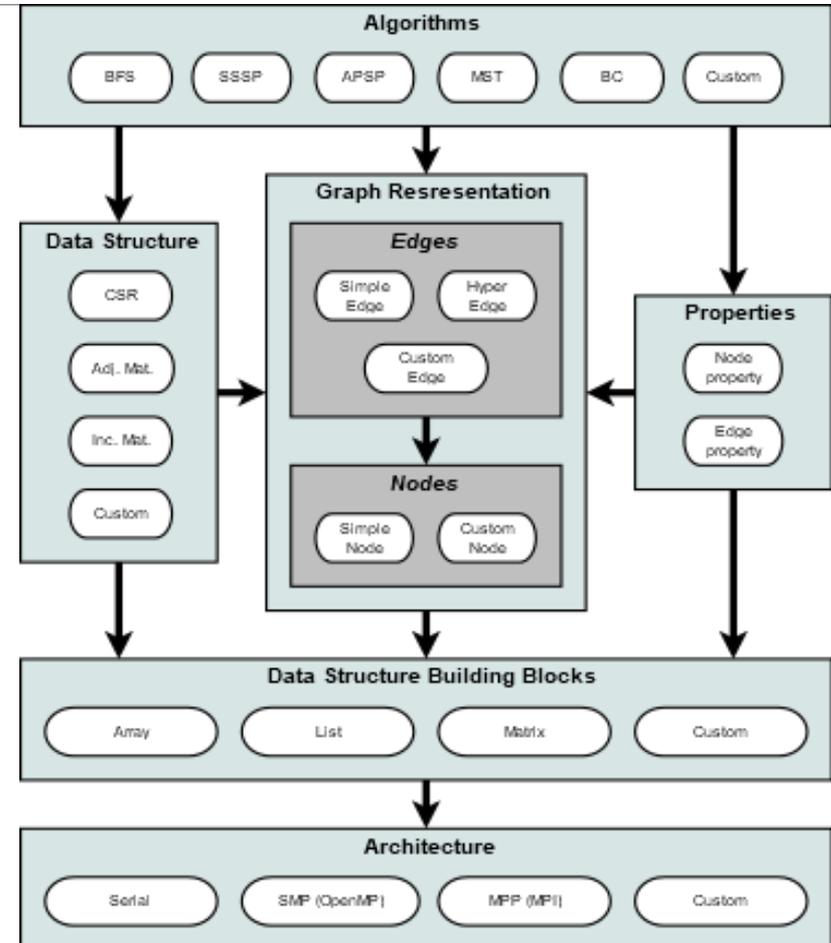
- Organize nodes and edges for efficient read and write operations

Properties

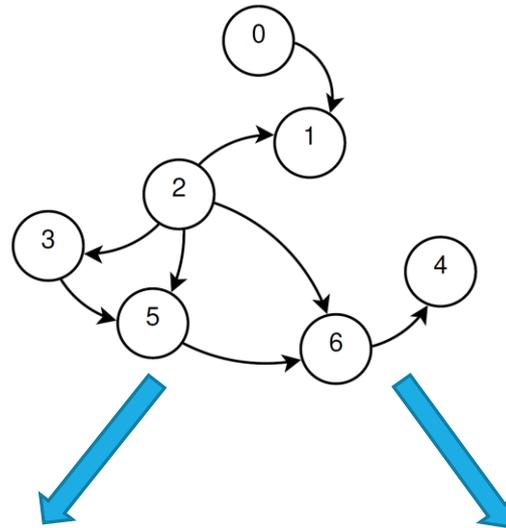
- Any edge/node property

Data structure building blocks

- “Atomic” data structures that used for construction of graph data structure



Benchmarking (1)



$$\mathbf{A} = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 \end{pmatrix}$$

Compressed Sparse Rows (CSR):

- row pointers = [0, 1, 1, 5, 6, 6, 7, 8]
- column ids = [1, 1, 3, 5, 6, 5, 6, 4]

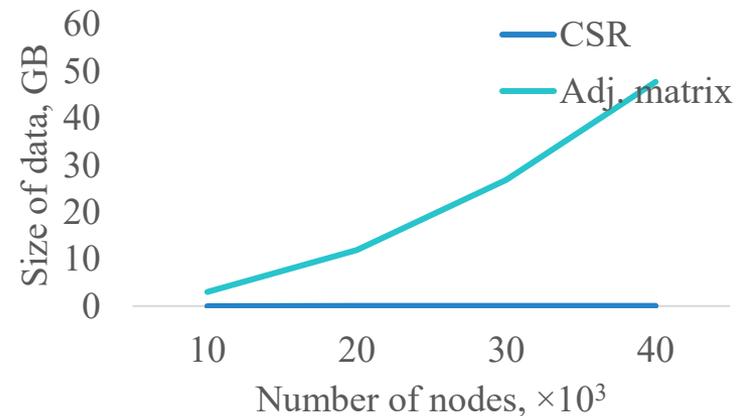
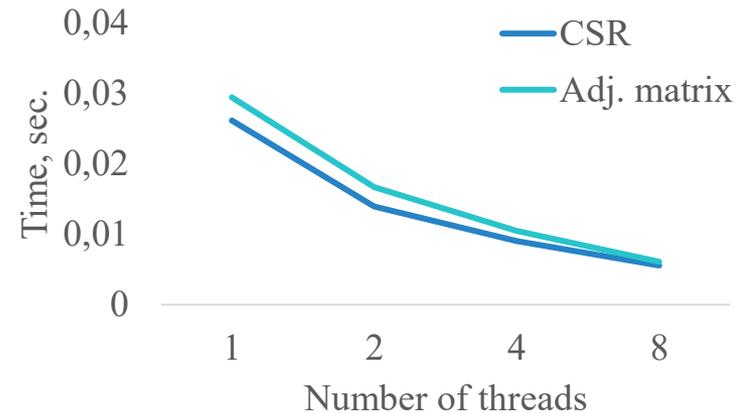
Benchmarking (2)

C++ implementation

BFS algorithm with CSR and
Matrix data structures

RMAT graph $\sim 50 \times 10^3$ nodes
and 16 edges per node

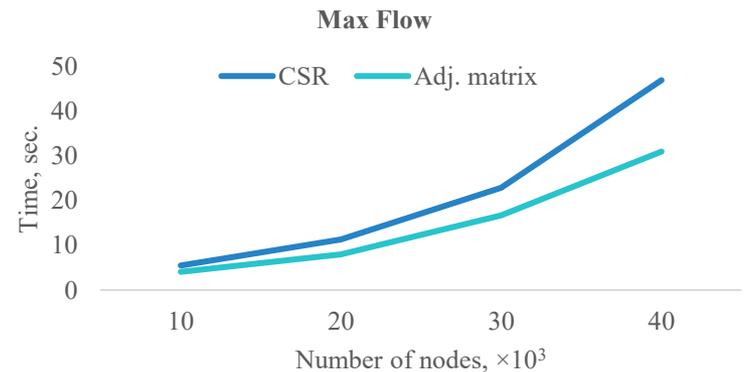
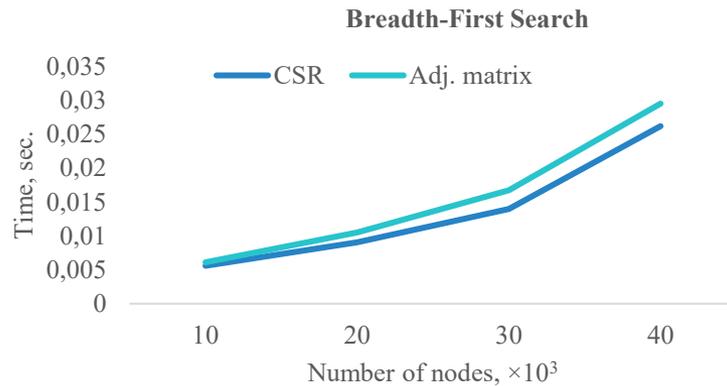
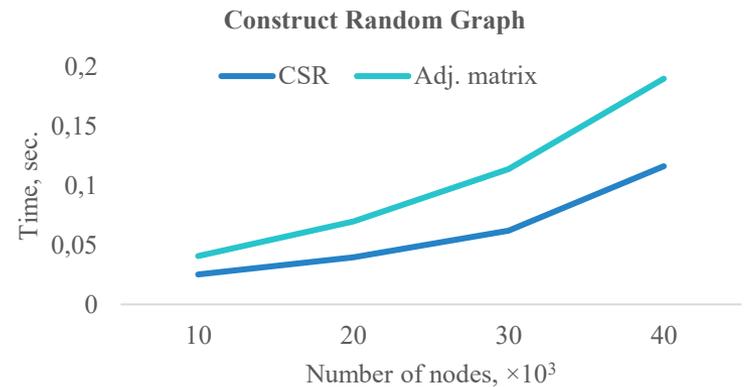
OpenMP scalability up to 8
threads



Benchmarking (3)

Different algorithms with CSR and Matrix data structures and Matrix

RMAT graphs from $\sim 10 \times 10^3$ to $\sim 40 \times 10^3$ nodes



Future research

More efficient data structures

- Navigation and modification with linear complexity

More algorithms

- Paths, flows, centralities, communities, etc.

MPI parallelization

- Adopt graph processing system for MPP parallelization

Parallelization

Development complexity		SMP	MPP (less than 50 nodes)	MPP (more than 50 nodes)
	Easy	NetworkX, igraph	ND	ND
	Medium	Now	To be done	GraphBLAS
	Hard	C/C++ development	ND	Parallel BGL

Questions?
